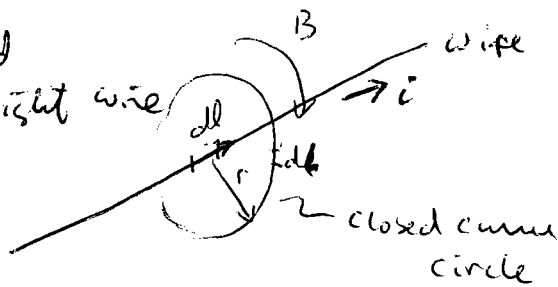


Using Ampere's Law

What is B field around straight wire



$$\int \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

Use Biot-Savart law to think about direction of B and path along which B is constant

$$d\vec{B} = \frac{\mu_0}{4\pi} i \frac{d\vec{l} \times \hat{r}}{r^2}$$

Keep your dl's straight!

B is a fn of r only!

B goes in direction show

⇒ Put thumb along i - fingers curl in direction of \vec{B}
 right

$$\vec{B} \cdot d\vec{l} = B dl$$

$$\int \vec{B} \cdot d\vec{l} = B \int dl = \mu_0 i$$

$$B 2\pi r = \mu_0 i$$

$$B = \frac{\mu_0 i}{2\pi r}$$

Right Hand Rule
 B around current
 bearing wire!

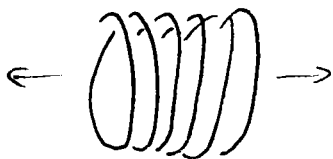
~~Field of a Solenoid and a Solenoid~~



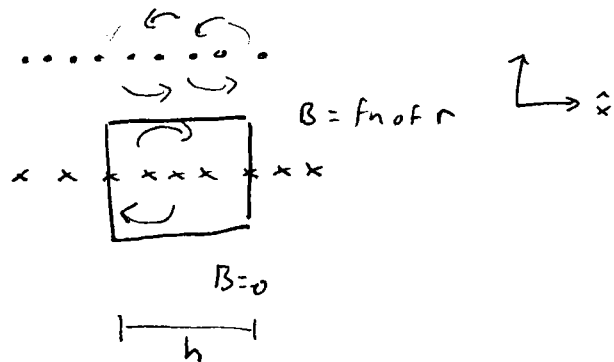
~~In Magnetostatics
 plays the role of ϵ_0 in electrostatics
 for electrostatics~~

Slinky

Field of an infinite Solenoid Tightly Packed N loops/length



Slinky



$$\int \vec{B} \cdot d\vec{l} = B h = \mu_0 i = \mu_0 n h i$$

$$\vec{B} = \mu_0 n i \hat{x} \quad \text{inside}$$

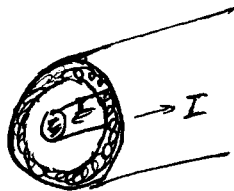
$$\vec{B} = 0 \quad \text{outside}$$

~ Sometimes plays role in magnetostatics

that // plate capacitor plays in electrostatics

Long Coaxial cable

Concentric conductors - each w/ i

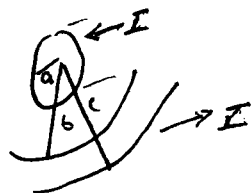


Find B $r < a$

$b > r > a$

$c > r > b$

$r > c$



Assume I is uniformly distributed thruout conductor

$r < a$



$$\int \vec{B} \cdot d\vec{l} = 2\pi r B = \mu_0 i_{enc1}$$

$$i_{enc1} = \frac{\pi r^2}{\pi R^2} I$$

Use Thumb/Fingers
to get
direction

$$|\vec{B}| = \frac{\mu_0}{2\pi r} \frac{\pi r^2}{\pi R^2} I = \frac{\mu_0 r I}{2\pi R^2}$$

$a < r < b$



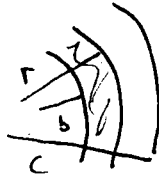
$$2\pi r B = \mu_0 I$$

$$|\vec{B}| = \frac{\mu_0 I}{2\pi r}$$

$$\int \vec{B} \cdot d\vec{l} = \mu_0 I$$

$b < r < c$

$$\int \vec{B} \cdot d\vec{l} = 2\pi r B = \mu_0 i_{enc1} = \mu_0 \left[I - \frac{I}{\pi(c^2 - b^2)} \pi(r^2 - b^2) \right]$$



Area element density in outer conductor is

$$\frac{I}{(\pi c^2 - \pi b^2)} = \frac{I}{\pi(c^2 - b^2)}$$

$$B = \frac{\mu_0 I}{2\pi r} \left[1 - \frac{\pi(r^2 - b^2)}{\pi(c^2 - b^2)} \right]$$

Note $r = c \Rightarrow B \rightarrow 0$

$r > c$

$B = 0$ because $i_{enc1} = 0$ for Amperian loop w/ $r > c$!

$$\int \vec{B} \cdot d\vec{l} = i_{enc1} \mu_0$$

Magnetic Induction

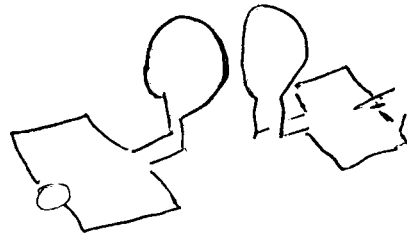
do demos

1830's Michael Faraday (England)
Joseph Henry (US)

⇒ do demos

Induction - A changing magnetic field induces a changing electric field

⇒ induced EMF's, induced currents



(observe a current due to induced EMF)

No changing fields
Magneto statics

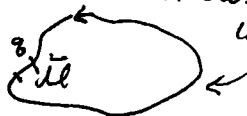
Kirchoff's rules

$$\sum V |_{\text{closed loop}} = 0$$

Also true in free space

$$\oint_C \vec{E} \cdot d\vec{l} = 0$$

(line integral) \oint_C work to move charge about a closed loop



With changing Magnetic field

$$\mathcal{E} = \oint \vec{E} \cdot d\vec{l} = - \frac{d\Phi_m}{dt}$$

Faraday's Law

True in wires/material
or

free space !!

\mathcal{E} True only instantaneously!

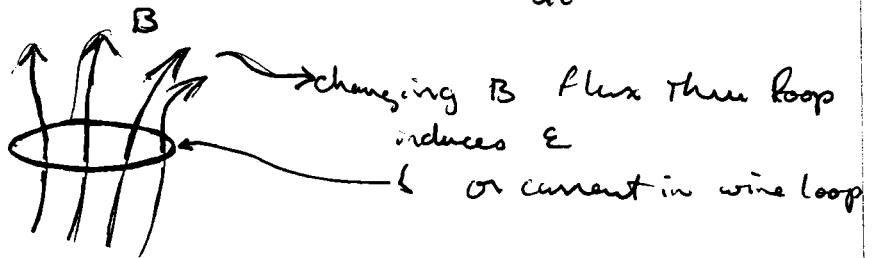
unless $\frac{d\Phi_m}{dt}$ is constant

So, Think abt wire loop

$$\mathcal{E} = \oint \vec{B} \cdot d\vec{\ell} = -\frac{d\Phi_m}{dt}$$

Dir geometry of loop

Dir B magnitude or angle will cause Δ in Magnetic flux

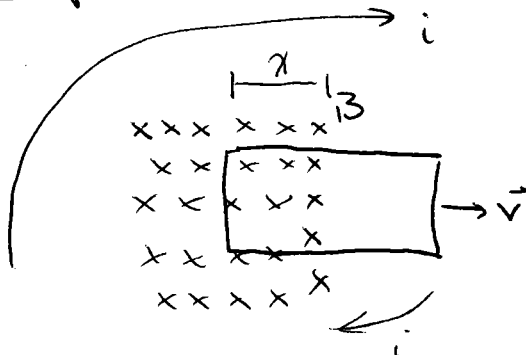


So we have induced \mathcal{E} ... current flows in loop
 \rightarrow induced current

What direction? \rightarrow NOTE the "-" in Faraday's law

Lenz's Law - An induced current in a closed conducting loop will appear in such a ~~way~~ direction that it opposes the change that produced it!

Examples



Explain induced i wants to \nearrow Φ_m - means it goes in what direction? wire arms!

$$\Phi_m = Blx$$

$$\mathcal{E} = -\frac{d\Phi_m}{dt} = -Bl\frac{dx}{dt} = -Blv$$

sets up a current $|i| = \frac{Blv}{R}$ - loop resistance
 Clockwise - why?

3 ways to look at -

① Φ_m being reduced
 induced i creates B that increased Φ_m



② Motional EMF
 \uparrow F x B
 \rightarrow v
 \uparrow v of
 For "conductor y " due to v

③ \leftarrow \uparrow i
 F produced by current works to slow down \vec{v}