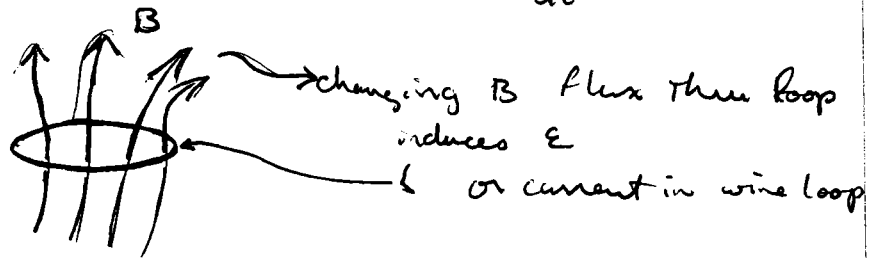


So, Think abt wire loop

$$\mathcal{E} = \oint \vec{B} \cdot d\vec{\ell} = -\frac{d\Phi_m}{dt}$$

Dirig geometry of loop

Dirig B magnitude or angle will cause Δ in Magnetic flux

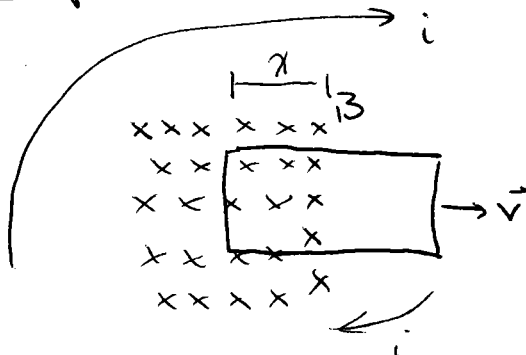


So we have induced \mathcal{E} ... current flows in loop
 \rightarrow induced current

What direction? \rightarrow NOTE the "-" in Faraday's law

Lenz's Law - An induced current in a closed conducting loop will appear in such a ~~way~~ direction that it opposes the change that produced it!

Examples



Explain induced i wants to \uparrow Φ_m - means it goes in what direction? wire arms!

$$\Phi_m = Blx$$

$$\mathcal{E} = -\frac{d\Phi_m}{dt} = -Bl\frac{dx}{dt} = -Blv$$

sets up a current $|i| = \frac{Blv}{R}$ - loop resistance
 Clockwise - why?

3 ways to look at -

① Φ_m being reduced
 induced i creates B that increased Φ_m

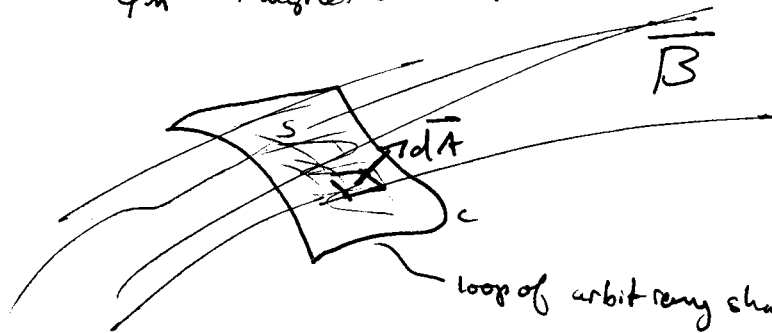


② Motional EMF
 \uparrow F x B
 \rightarrow v
 \uparrow v of
 For "conductor y" due to v

③ \leftarrow F
 F produced by current works to slow down \vec{v}

what is Φ_m

$\Phi_m \equiv$ Magnetic Flux thru the loop



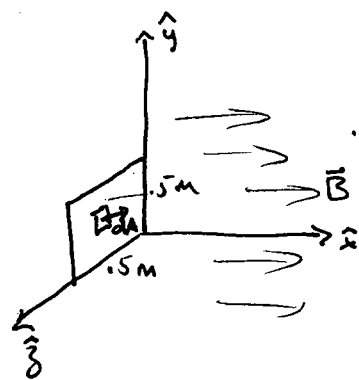
loop of arbitrary shape - ~~surface~~
A surface, S , spans the loop C

$$\int_S \vec{B} \cdot d\vec{A} = \Phi_m$$

Think of this exactly as you thought of $\int E \cdot dA$ for Gauss's Law

But surface is NOT closed
and use E instead of B

Simple example of Magnetic Flux calculation



.5 m square loop in $y-z$ plane

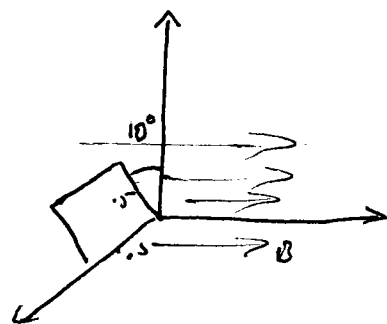
\vec{B} uniform - 2 T est \hat{x} in \hat{x} direction

$$\vec{B} \cdot d\vec{A} = B dA$$

$$\int \vec{B} \cdot d\vec{A} = |B| \int dA = BA = 2 \text{ T} (.5 \text{ m})^2 = .5 \text{ T} \cdot \text{m}^2$$

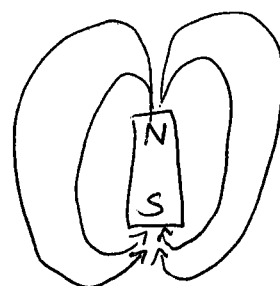
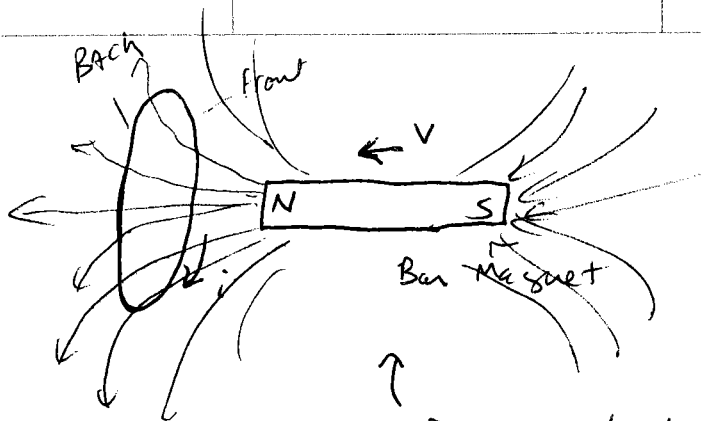
same problem:

except loop now rotated



$$d\vec{A} \cdot \vec{B} = |B| |dA| \cos \theta$$

$$\int \vec{B} \cdot d\vec{A} = |B| \cos \theta \int dA = (\cos 10^\circ) .5 \text{ T} \cdot \text{m}^2$$



Bar magnet looks like a dipole for electrostatics

ϕ_m increases

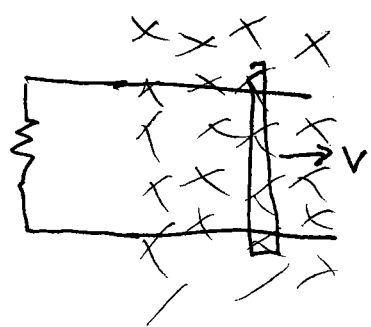
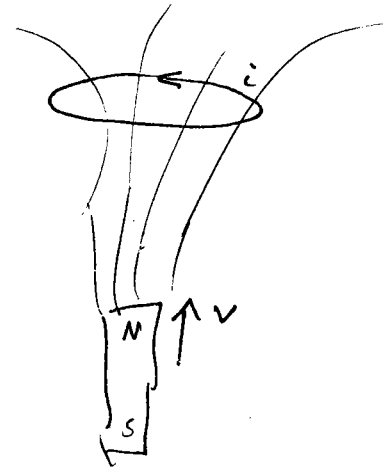
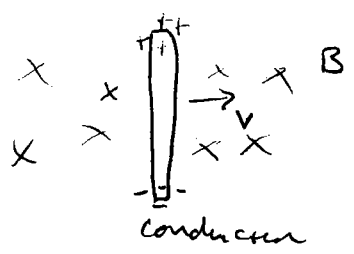
B due, induced i decreases B

Note:

Motional EMF

vs.

EMF induced by changing B field



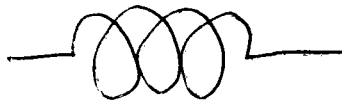
Sometimes Both — can think of either way (not both added)

$\mathcal{E} = IR$

100 SHEETS FULLER 9 SQUARE
 40 SHEETS FULLER 2 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 3 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 4 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 5 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 6 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 7 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 8 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 9 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 10 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 11 1/2 LASER 9 SQUARE
 40 SHEETS FULLER 12 1/2 LASER 9 SQUARE

National Bureau of Standards
 Gaithersburg, MD 20899

$$\mathcal{E} = -L \frac{di}{dt}$$



Symbol of inductor
in circuit

$$\mathcal{E} = -L \frac{di}{dt} = -L \frac{d^2q}{dt^2}$$

Remember $\mathcal{E} = \frac{1}{C}$

$\Sigma V = 0$ eqn

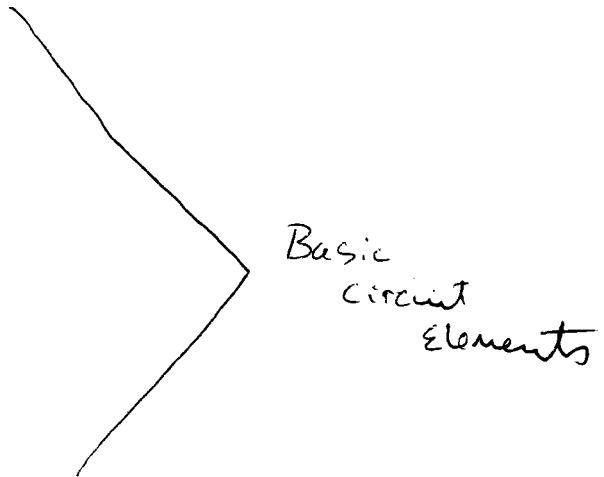
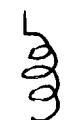
$$V = iR = \frac{dq}{dt}$$



$$Q/C = V$$



$$\mathcal{E} = -L \frac{d^2q}{dt^2}$$

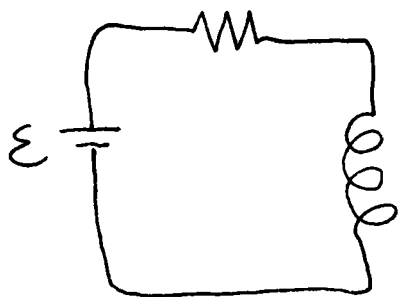


Basic
circuit
elements

inductors:

- will NOT do RL, RLC circuits
- will have to calculate inductances, L
- " " " " \mathcal{E} using or something using L

Energy & The Magnetic Field



$$\mathcal{E} = iR + L \frac{di}{dt}$$

$$\mathcal{E}i = i^2 R + Li \frac{di}{dt}$$

$$P = iV$$

Power out of EMF

Power
dissipated
by Resistor

Power
in or
out of
inductor

rate at which energy stored in the Magnetic field ←

$$\text{Power} = \frac{dU_B}{dt} = Li \frac{di}{dt}$$

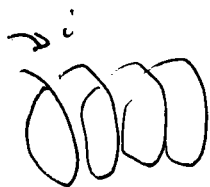
$$dU_B = Li di$$

$$\int U_B = \int_0^i Li di = \frac{1}{2} Li^2$$

Energy stored in an inductor carrying current i
(similar to $U = \frac{1}{2} CV^2$ for capacitors!)

Example

Consider a Solenoid carrying a current i
 n turns/length



What is the Energy density of the
Magnetic field inside?

Find in terms of B .

$$B_{\text{solenoid}} = \mu_0 n i \quad \text{inside}$$

$$= 0 \quad \text{outside}$$

what direction?

$$u_B = \text{energy density} = \frac{U_B}{Al} \quad \text{Area} \times \text{length}$$

$$u_B = \frac{1}{2} L i^2 / Al$$

Recall for solenoid

$$\Phi_M \propto i \quad \Phi_M = L i \quad \begin{matrix} \nearrow \\ \text{\# Turns} \end{matrix}$$

$$\text{or } L = \frac{\Phi_M}{i} = \frac{(BA)(nl)}{i}$$

$$B_{\text{solenoid}} = \mu_0 n i \quad \rightarrow \quad L = \mu_0 n^2 A l$$

Sub into u_B

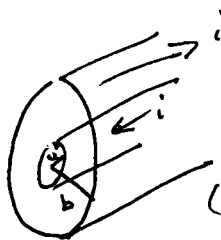
$$u_B = \frac{1}{2} \frac{\mu_0 n^2 A l i^2}{A l} = \frac{1}{2} \mu_0 i^2 n^2 = \frac{B^2}{2\mu_0}$$

$$\boxed{u_B = \frac{B^2}{2\mu_0}}$$

derived w/ Solenoid example
True in general!

Exactly Analogous to $u_E = \frac{1}{2} \epsilon_0 E^2$

Example



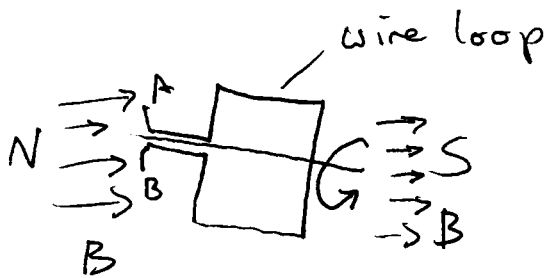
Concentric conducting shells
COAXIAL

(a) Find B everywhere

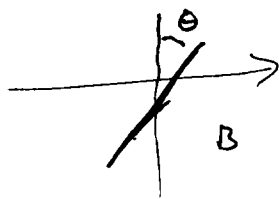
(b) Find total U/l for system

AC Circuits

NOT covered in this course but ~



Flux depends on Angle



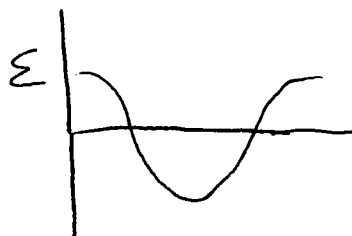
$$\phi \propto \cos \theta$$

$$\theta = \omega t$$

$$\therefore \frac{d\phi}{dt} \sim \epsilon \sim \sin \theta$$

Know your limitations!

Plot V_{AB} induced



Sinusoidally
Varying ϵ

Alternating current

\Rightarrow Time dependence
in everything!

\Rightarrow More complex than
Direct Current

\Rightarrow This is what you get out of
the wall

60 Hz frequency

look for it as Noise source.