

Physics 113 - November 7, 2006

LAST
TIME

$$\vec{L} = \vec{I} \alpha$$

Angular Acceleration

Torque

moment of inertia

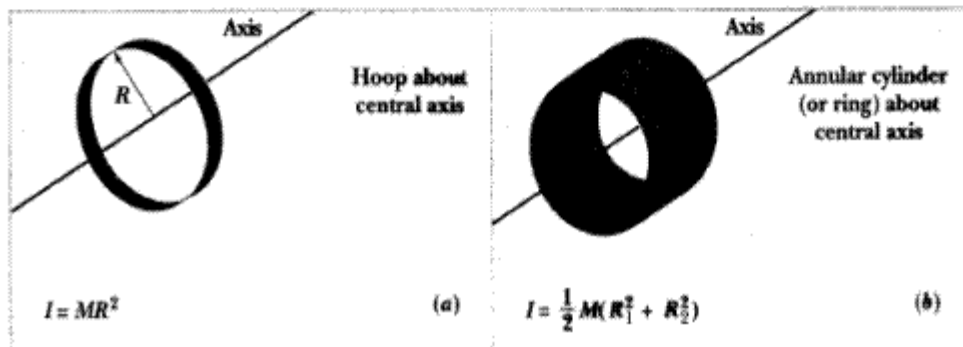
This is the rotational analogue of $F=ma$
Vector Aspect of eqn very imp.
but ignored 'till now.

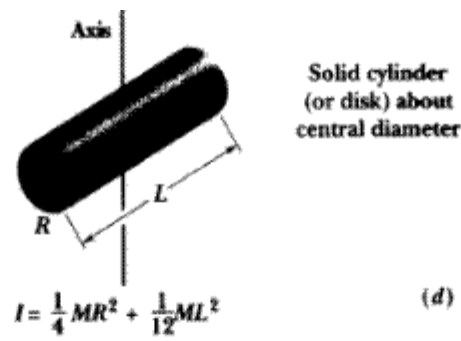
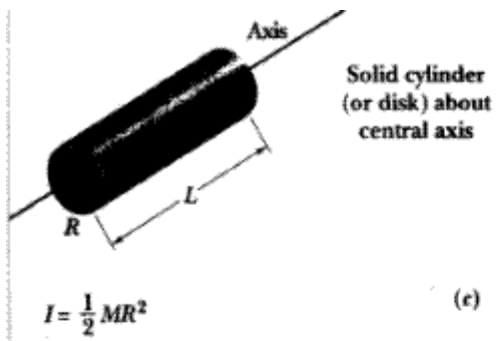
$\vec{L} \equiv \text{torque} \sim r F \dots$ more complication to come
Applied force
Distance to axis of rotation
from pt. of applied force

I \equiv moment of Inertia

$$\underline{I} = \int_{\text{volume}} r^2 dm = \int_{\text{volume}} r^2 \rho dv$$

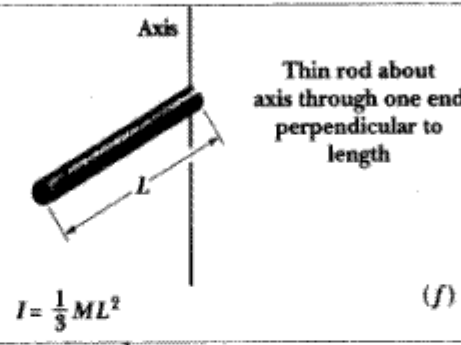
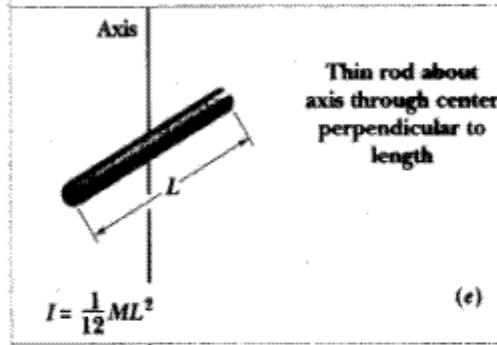
Many I are already calculated for you
can look up in a table



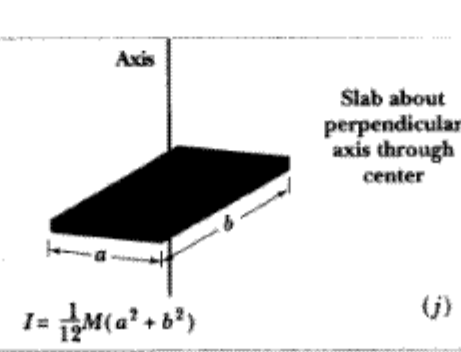
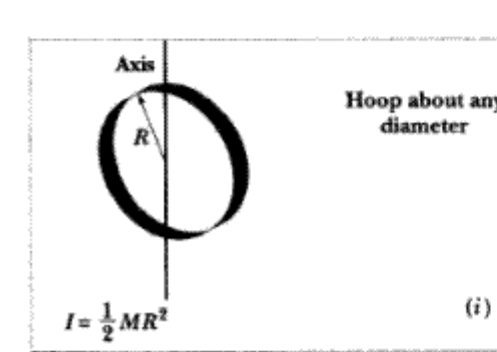
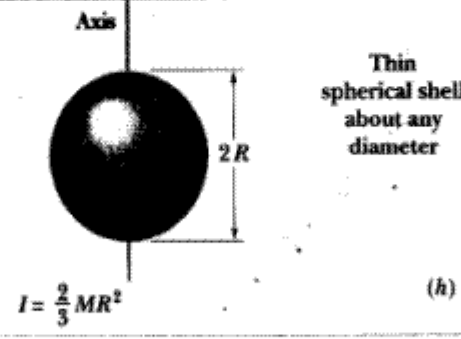
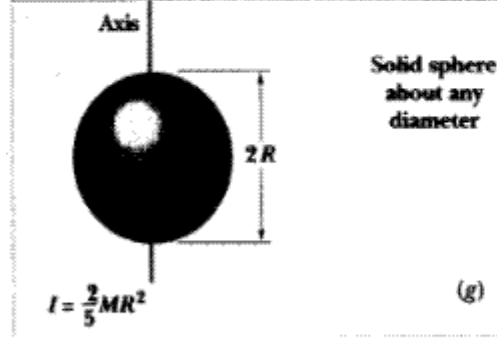


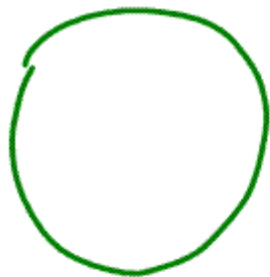
$$I = \int r^2 dm$$

⤵



As more of
mass is
farther from
axis of
Rotation
I → larger





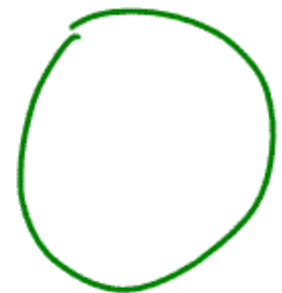
Hollow sphere

$$I = \frac{2}{3} MR^2$$



Wheel

$$I = MR^2$$



Solid sphere

$$I = \frac{2}{5} MR^2$$

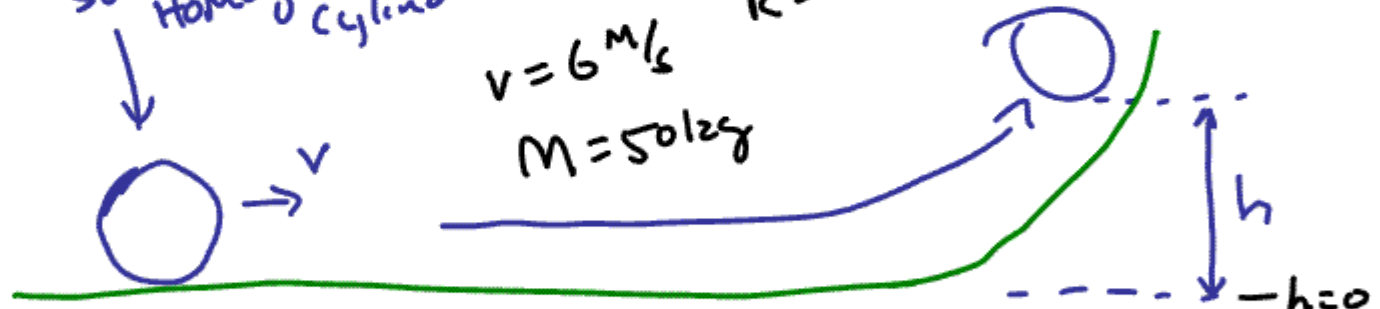
How far up ramp does cyl. climb?

NOT slipping

Solid Homogenous cylinder



$v = 6 \text{ m/s}$
 $M = 50 \text{ kg}$
 $R = 15 \text{ cm}$



E_{START}

E_{end}

~~PE~~
 $\rightarrow 0$

+ KE

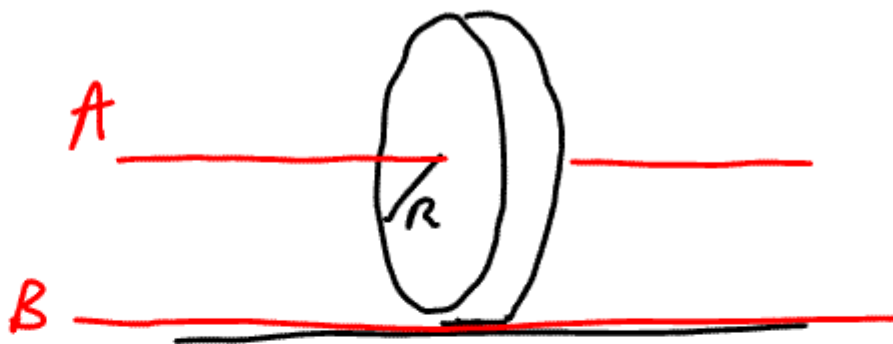
TRANSLATION

+ KE

ROTATION

$$= mgh$$

$$\frac{1}{2} M v^2 + \frac{1}{2} I \omega^2 = mgh$$



$$I_A = \frac{1}{2} M R^2 \quad (\text{from table})$$

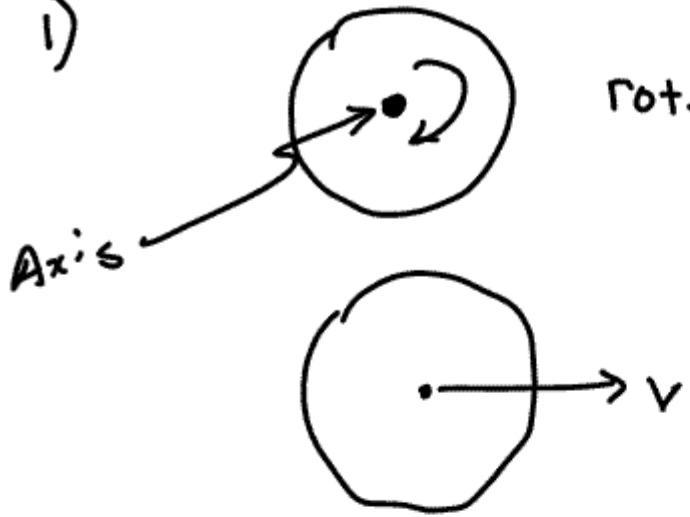
$$I_B = I_A + M r^2$$

parallel axis theorem
Dist of Axis B from Axis A
Axes //

$$I_B = I_A + M R^2$$

$$I_B = \frac{3}{2} M R^2$$

1)



rotation abt C.M.

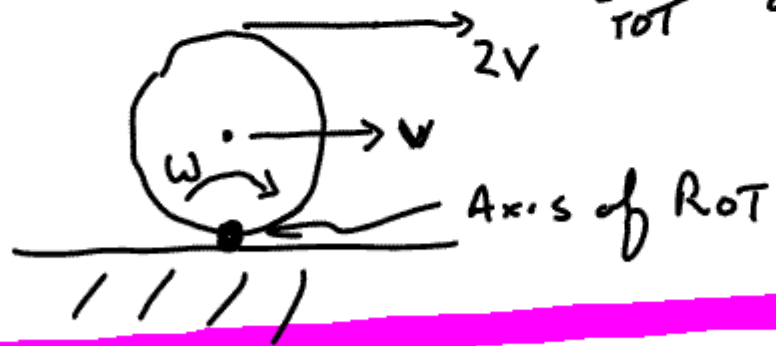
$$KE = \frac{1}{2} I \omega^2 = \frac{1}{2} \left(\frac{1}{2} M R^2 \right) \frac{v^2}{R^2}$$

Moving C.M

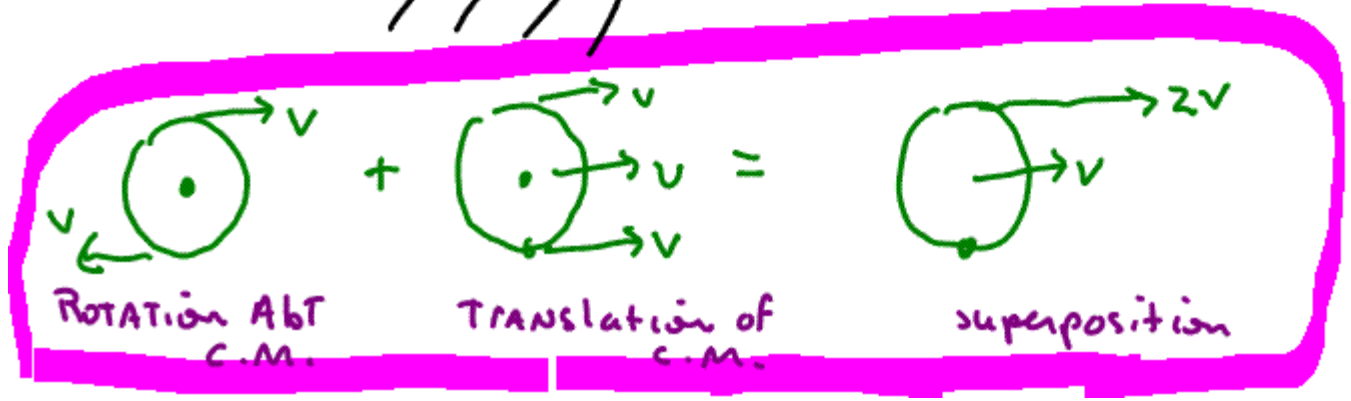
$$KE = \frac{1}{2} M v^2$$

$$KE_{TOT} = KE_T + KE_{ROT}$$

2)



$$KE_{TOT} = \frac{1}{2} M v^2 + \frac{1}{4} M v^2 = \frac{3}{4} M v^2$$



2) Body rotating abt Axis at bottom
C.M. NOT moving

$$KE_{\text{TOT}} = \frac{1}{2} I \omega^2 = \frac{1}{2} \left(\frac{3}{2} MR^2 \right) \omega^2$$

↑
 $\frac{v^2}{R^2}$

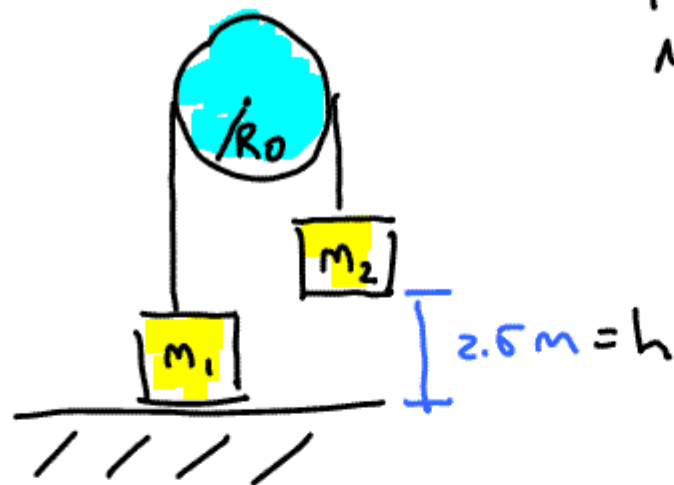
$$KE_{\text{TOT}} = \frac{3}{4} Mv^2$$

$$\frac{1}{2} Mv^2 + \frac{1}{2} I \omega^2 = Mgh$$

$$\frac{3}{4} Mv^2 = Mgh$$

$$h = \frac{3}{4} \frac{v^2}{g}$$

10-65
Giambati.



$$M_1 = 25.0 \text{ kg}$$
$$M_2 = 38.0 \text{ kg}$$

Pulley: uniform cylinder
w/ radius $R_0 = 0.3 \text{ m}$
and Mass $M = 4.8 \text{ kg}$

Init m_1 on ground m_2 at rest 2.5 m above ground
Assume rope massless and does not slip

System released \rightarrow what is speed of m_2 just before it hits the ground?

Two ways to solve this problem $\begin{cases} \rightarrow \text{Energy conservation} \\ \rightarrow \text{Newton's Laws} \end{cases}$

Energy Conservation

$$E_{\text{START}} = E_{\text{end}}$$

$\uparrow v$ $\downarrow v$

$$m_2 g h = m_1 g h + \frac{1}{2} M_1 v_1^2 + \frac{1}{2} M_2 v_2^2 + \frac{1}{2} I \omega^2$$

$$v_1 = v_2 = v = R_0 \omega$$

$$I = \frac{1}{2} M R_0^2$$

$$M_2 g h = M_1 g h + \frac{1}{2} (M_1 + M_2) v^2 + \frac{1}{2} \left(\frac{1}{2} M R_0^2 \right) \frac{v^2}{R_0^2}$$

Solve for v

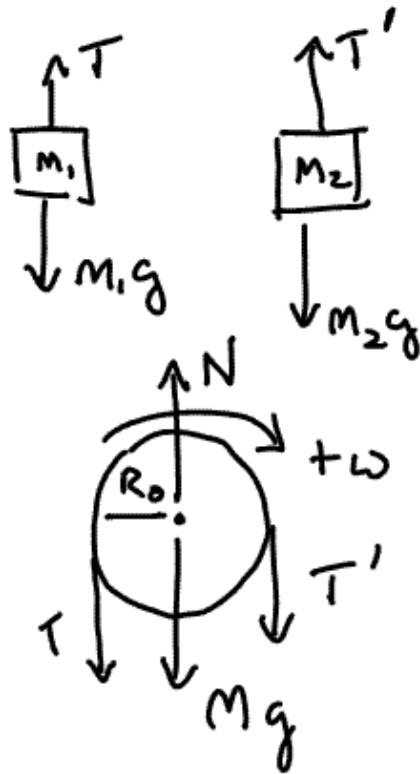
$$v = \pm \sqrt{\frac{(M_1 - M_2) g h}{\frac{M_1}{4} + \frac{M_2}{2} + \frac{M_1}{2}}} = \pm 1.4 \text{ m/s}$$

(1.4 m/s)

using Newton's Laws



FBD's



With massive pulley
 $T \neq T'$

$$\sum F_y = m_1 a$$

$$m_1 a = T - m_1 g$$

$$\sum F_y = m_2 a$$

$$m_2 a = m_2 g - T'$$

Pulley

$$\sum \tau = I \alpha$$

$$R_0 T' - R_0 T = I \frac{a}{R_0}$$

$$\frac{1}{2} M R_0^2$$

3 eqns 3 unknowns

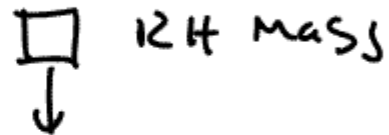
$$a = \frac{(m_2 - m_1)g}{\frac{1}{2}M + m_1 + m_2}$$

const a

$$\hookrightarrow a = 0.4 \text{ m/s}^2$$

$$v_2^2 = v_{02}^2 + 2ah$$

$$v_2^2 = (2)(.4)(2.5) = 2$$



$$v_2 = 1.4 \text{ m/s}$$

Both methods give the same answer.