

Physics 113 - October 26, 2006

■ projects?

■ I'll be asking for Topics/groups soon

Last Time

$$\vec{F} = \frac{d\vec{p}}{dt} = \frac{d(m\vec{v})}{dt}$$

$$\vec{p} \equiv m\vec{v} \equiv \text{Momentum}$$

Momentum always conserved
for "isolated" systems

$$\sum \vec{p}_i = \sum \vec{p}_f \quad \underline{\text{vector}} \quad \underline{\text{eqn}}$$

Energy conservation

Always true ... Not always useful

IF KE is conserved

$$\underline{\underline{\sum KE_i = \sum KE_f}}$$

Elastic collision

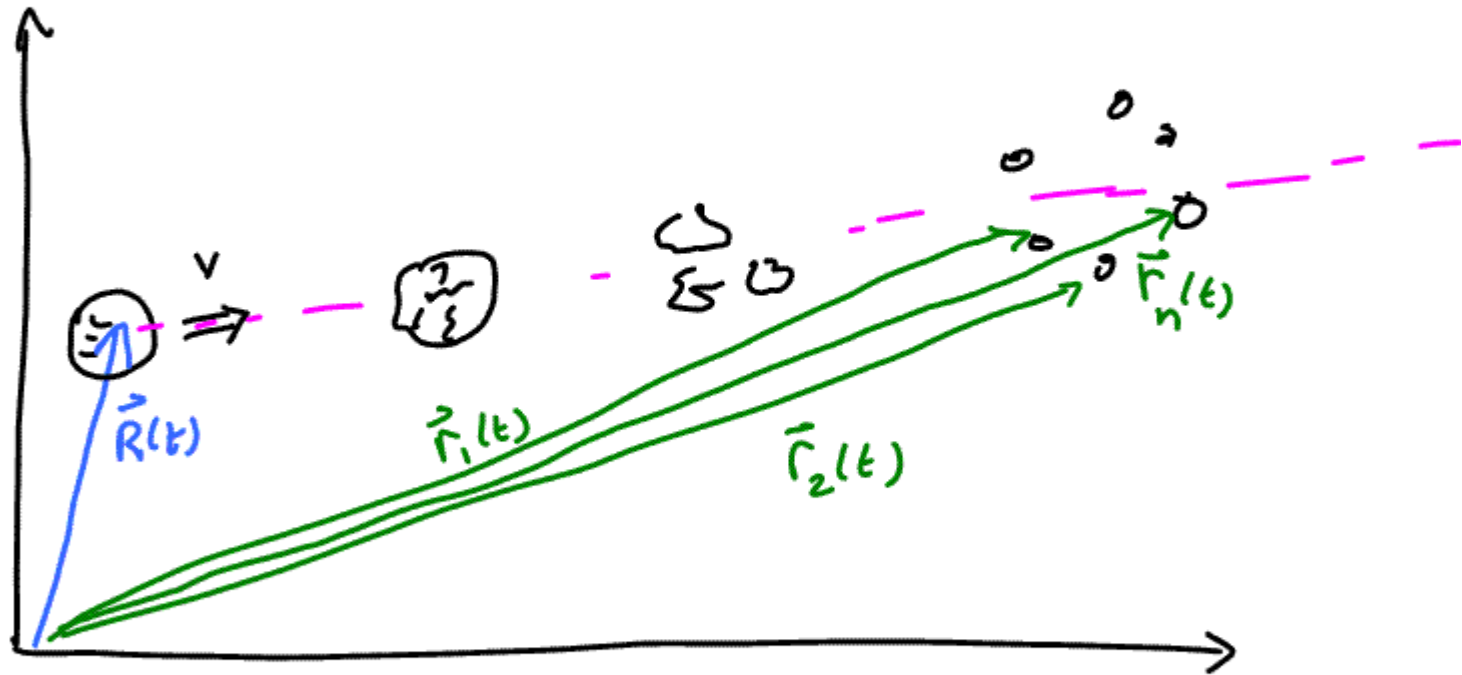
Think billiards

IF KE is NOT conserved

$$\sum KE_i \neq \sum KE_f$$

inelastic
collision

Center of Mass , Center of Mass
coordinates



Momentum Conservation

$$\sum \vec{P}_i = \sum \vec{P}_f$$

$$M \vec{V} = m_1 \vec{V}_1 + m_2 \vec{V}_2 + \dots + m_n \vec{V}_n$$

$$M \frac{d\vec{R}}{dt} = m_1 \frac{d\vec{r}_1}{dt} + m_2 \frac{d\vec{r}_2}{dt} + \dots + m_n \frac{d\vec{r}_n}{dt}$$

$$M \vec{R} = m_1 \vec{r}_1 + m_2 \vec{r}_2 + \dots + m_n \vec{r}_n$$

$$\left. \begin{array}{l} \vec{R} = (X, Y, Z) \\ \vec{r}_1 = (x_1, y_1, z_1) \\ \vdots \end{array} \right\} \rightarrow \begin{array}{l} M X = m_1 x_1 + m_2 x_2 + \dots + m_n x_n \\ M Y = m_1 y_1 + m_2 y_2 + \dots + m_n y_n \\ M Z = m_1 z_1 + \dots + m_n z_n \end{array}$$

\vec{R} — or. X, Y, Z center-of-mass coordinates

$$X = \frac{m_1 x_1 + m_2 x_2 + \dots + m_n x_n}{M}$$

$$M = m_1 + m_2 + \dots + m_n$$

discrete
masses

$$X_{cm} = \frac{\sum_i m_i x_i}{\sum_i m_i}$$

mass weighted
x position
of system

$$Y_{cm} = \frac{\sum_i m_i y_i}{\sum_i m_i}$$

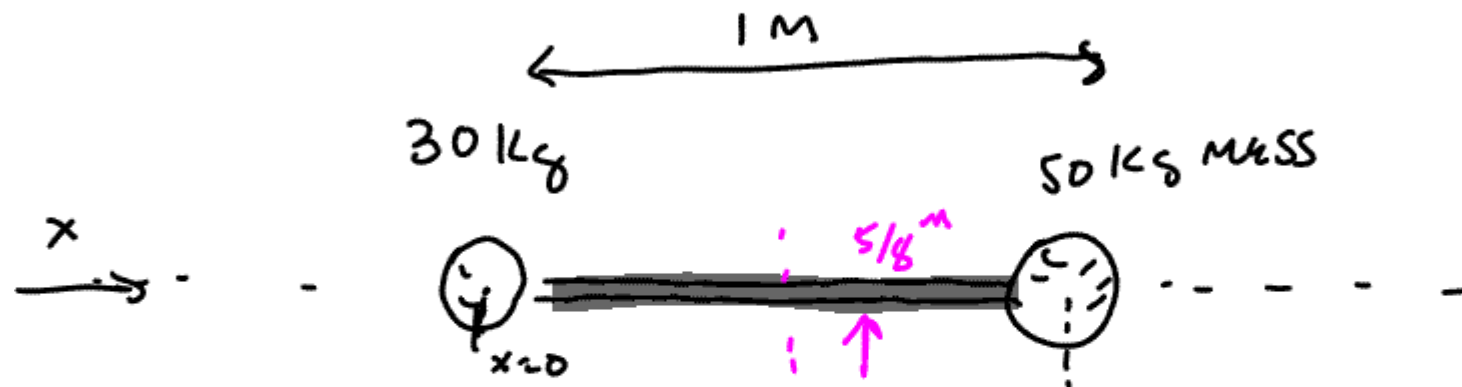
$$\vec{R} = \frac{\sum_i m_i \vec{r}_i}{\sum_i m_i}$$

$$Z_{cm} = \frac{\sum_i m_i z_i}{\sum_i m_i}$$

Important

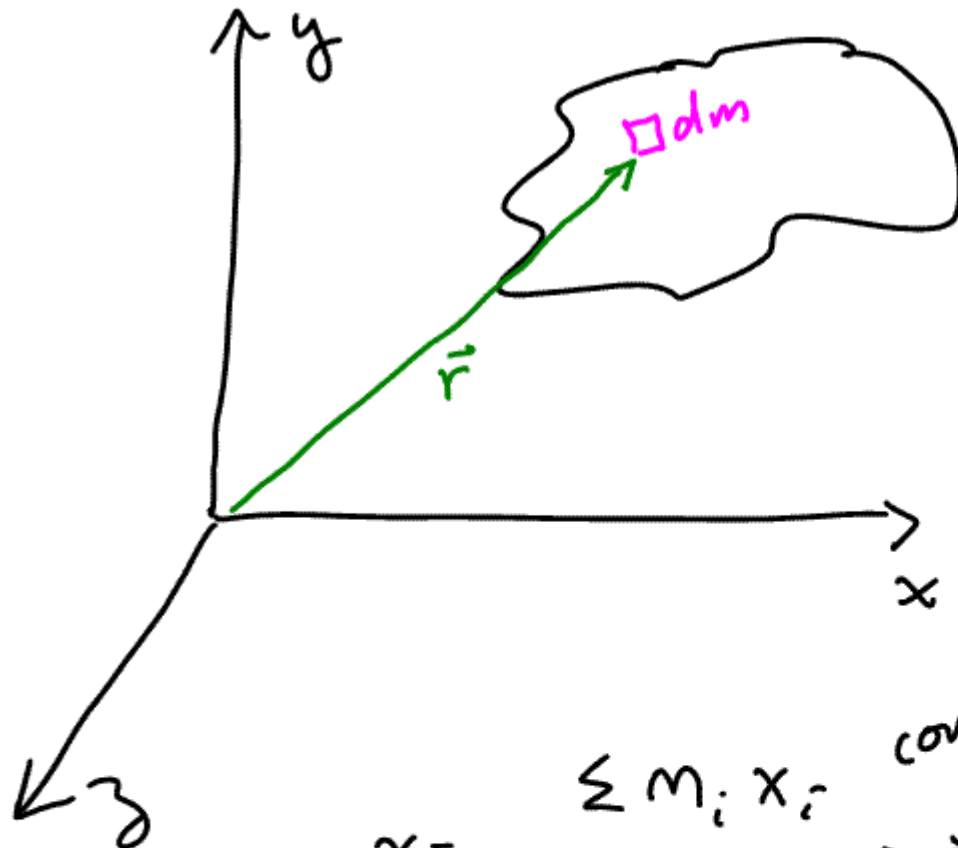
Center of Mass Coordinates

Can consider a system of bodies to be equivalent to one body w/ same (total) mass located at the center-of-mass



where is CM of system

$$x_{cm} = \frac{\sum x_i m_i}{\sum m_i} = \frac{x_1 m_1 + (1m)(50)}{30 + 50} = \frac{5}{8} m$$



$\int_v = \int_{vol}$
 |||
 integration over TOTAL volume

C.M. coords for continuous body

$$x = \frac{\sum M_i x_i}{\sum M_i} \xrightarrow{\text{continuous limit}} \frac{\int x dm}{\int_{vol} dm}$$

TOTAL MASS

$$Y = \frac{\int_v y dm}{\int dm}$$

$$Z = \frac{\int_v z dm}{\int dm}$$

Important

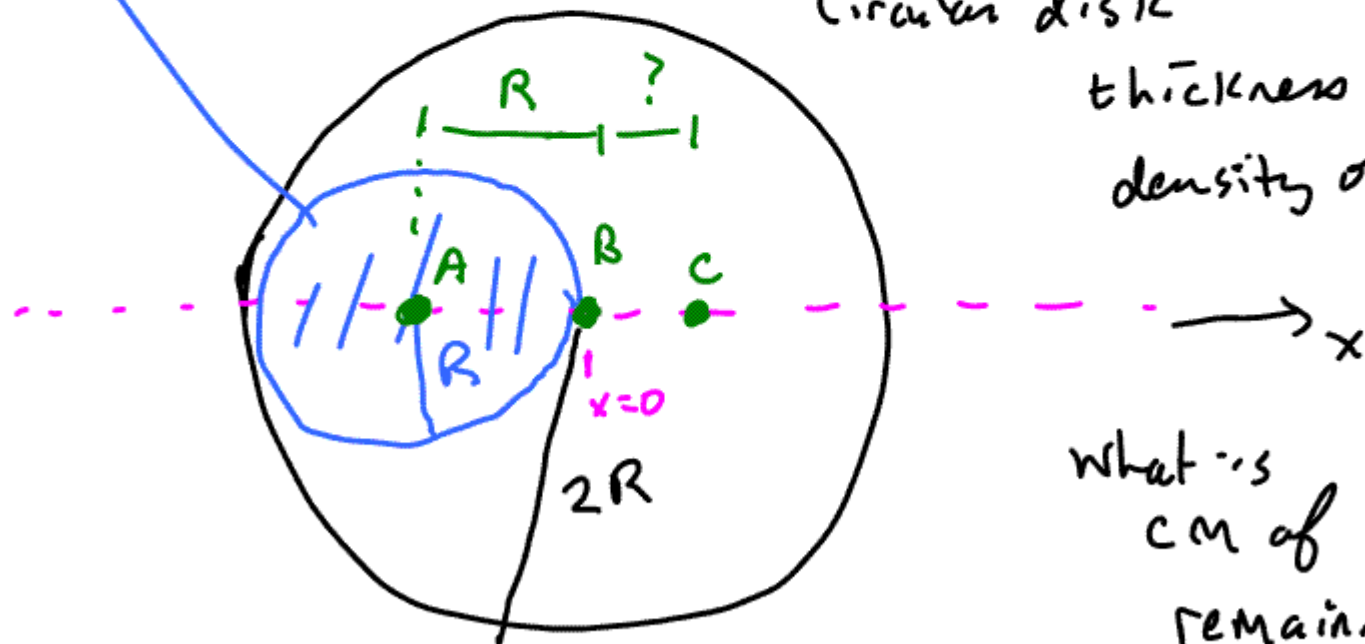
EXAMPLE

Remove circular plug

$$\vec{R} = \frac{\int_V \vec{r} dm}{\int_V dm}$$

Circular disk

thickness of t
density of ρ



What is
CM of
remaining
piece along x



$$0 \equiv X_B = \frac{M_{\text{plus}} X_A + M_{\text{disk-plus}} X_C}{M_{\text{plus}} + M_{\text{disk-plus}}}$$

$$M_P X_A + M_{D-P} X_C = 0$$

$$X_C = \frac{-M_P X_A}{M_{D-P}}$$

$$X_C = - \frac{\rho \pi R^2 t X_A}{\rho \pi (2R)^2 t - \rho \pi R^2 t}$$

$$X_C = \frac{1}{3} R$$