

- Concept Map

Lect Sept 5

- Problems with Website? / Downloads of .docs?

- e-mail roster

- Workshop signups

<https://spider.pas.rochester.edu/signups/PHY113-F02/>

Last time:

→ Went thru syllabus + discussed how to approach course

→ Questions?

→ Spent a few minutes talking about the Scientific Philosophy of Physics and some of the things that make drive it to be what it is.

Precise Measurement / quantification

→ Mathematics ... Number

→ System of units

System International

MKS Mass = kg Length = M Time = s

cgs

g

cm

s

Br. & Int'l. Eng. English
Engineering System

slug inch foot s

Tennis Ball

$0 \rightarrow$

Introduce vectors and Scalars

Will not do significant figures
ESTIMATION ↴

Should know how to do

Vectors, Dimensional Analysis, conversions
Will do as we go!

Lets START studying the world around us
Sit on the ground for 2 hours
What do you see?

Motion ... change ... what causes change

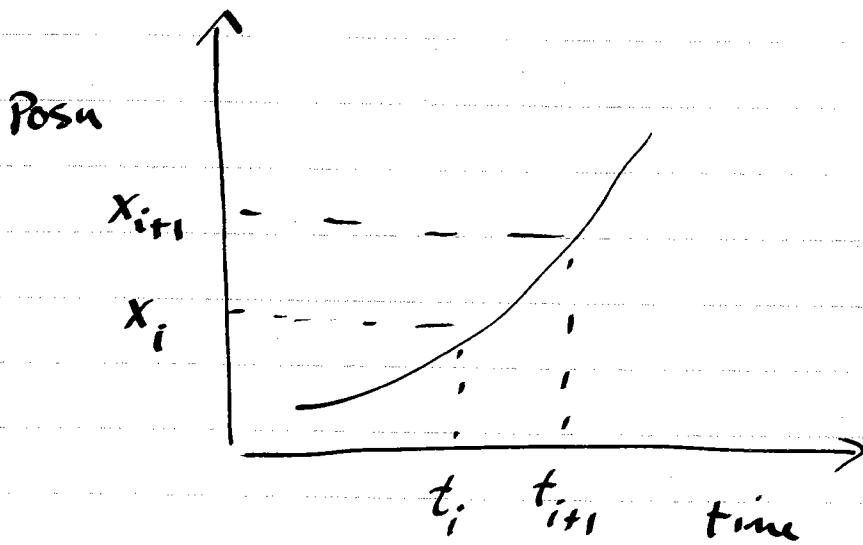
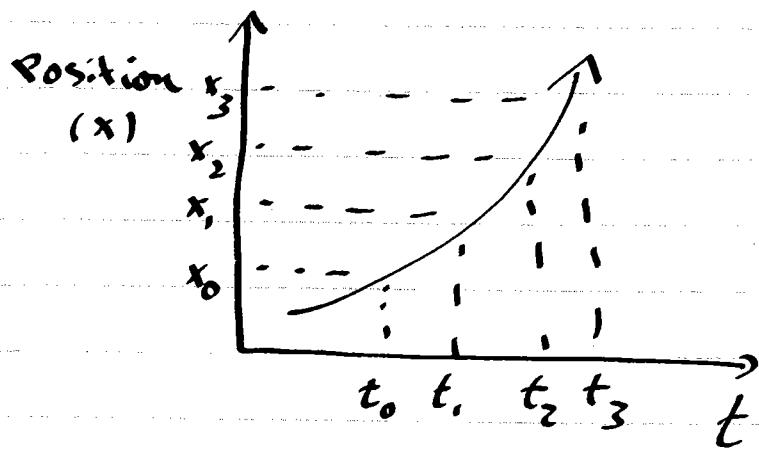
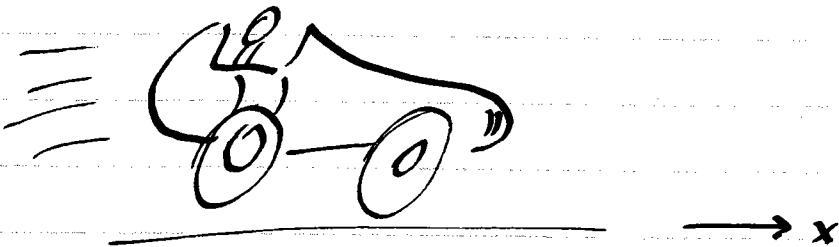
Let us begin by studying Motion
one dimension for simplicity

one dimensional kinematics



9/6/01

1 dimensional Motion (1d kinematics)



Ave. Speed over interval is

$$\frac{x_{i+1} - x_i}{t_{i+1} - t_i} = \frac{\Delta x}{\Delta t} \text{ m/s}$$

units

Ave Velocity is $\frac{\Delta x}{\Delta t}$ m/s in +x direction

Speed has magnitude only

Velocity has magnitude + direction

1 d motion ... direction determined
by sign

Suppose you want the instantaneous velocity,
at time t_i :

$$v = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$$

$$t_{i+1} \rightarrow t_i$$

Standard definition
of derivative

Suppose we look at a drag race

what does this look like

Motion

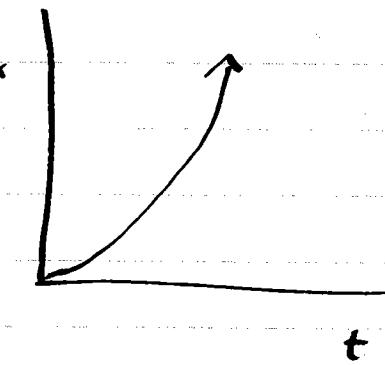


Table A-4 Properties of Derivatives and Derivatives of Particular Functions

Linearity

1. The derivative of a constant times a function equals the constant times the derivative of the function:

$$\frac{d}{dt} [Cf(t)] = C \frac{df(t)}{dt}$$

2. The derivative of a sum of functions equals the sum of the derivatives of the functions:

$$\frac{d}{dt} [f(t) + g(t)] = \frac{df(t)}{dt} + \frac{dg(t)}{dt}$$

Chain rule

3. If f is a function of x and x is in turn a function of t , the derivative of f with respect to t equals the product of the derivative of f with respect to x and the derivative of x with respect to t :

$$\frac{d}{dt} f(x) = \frac{df}{dx} \frac{dx}{dt}$$

Derivative of a product

4. The derivative of a product of functions $f(t)g(t)$ equals the first function times the derivative of the second plus the second function times the derivative of the first:

$$\frac{d}{dt} [f(t)g(t)] = f(t) \frac{dg(t)}{dt} + \frac{df(t)}{dt} g(t)$$

Reciprocal derivative

5. The derivative of t with respect to x is the reciprocal of the derivative of x with respect to t , assuming that neither derivative is zero:

$$\frac{dx}{dt} = \left(\frac{dt}{dx} \right)^{-1} \quad \text{if} \quad \frac{dt}{dx} \neq 0$$

Derivatives of particular functions

6. $\frac{dC}{dt} = 0$ where C is a constant 9. $\frac{d}{dt} \cos \omega t = -\omega \sin \omega t$

7. $\frac{d(t^n)}{dt} = nt^{n-1}$ 10. $\frac{d}{dt} e^{bt} = be^{bt}$

8. $\frac{d}{dt} \sin \omega t = \omega \cos \omega t$ 11. $\frac{d}{dt} \ln bt = \frac{1}{t}$

Table A-5 Integration Formulas^t

1. $\int A dt = At$

5. $\int e^{bt} dt = \frac{1}{b} e^{bt}$

2. $\int At dt = \frac{1}{2}At^2$

6. $\int \cos \omega t dt = \frac{1}{\omega} \sin \omega t$

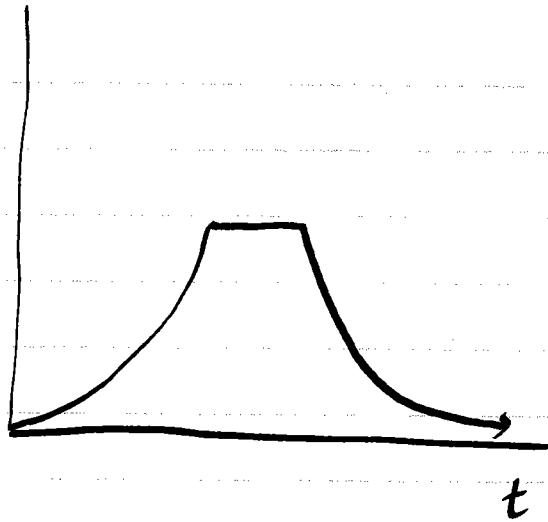
3. $\int At^n dt = A \frac{t^{n+1}}{n+1} \quad n \neq -1$

7. $\int \sin \omega t dt = -\frac{1}{\omega} \cos \omega t$

4. $\int At^{-1} dt = A \ln t$

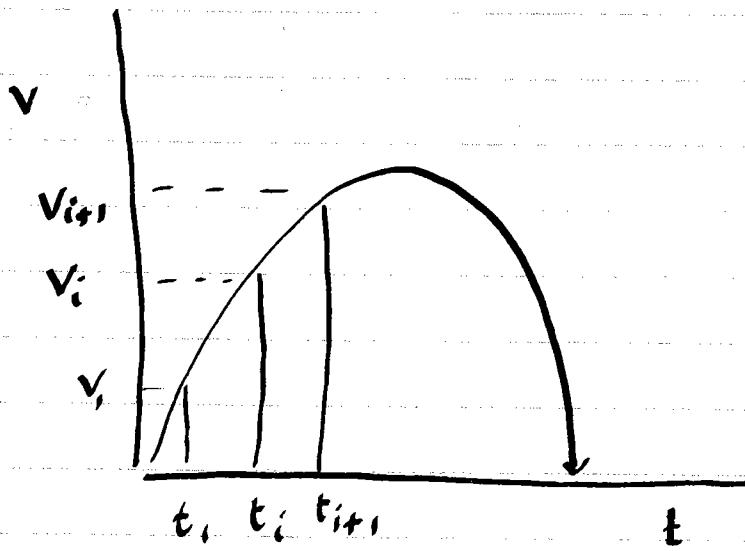
^tIn these formulas, A , b , and ω are constants. An arbitrary constant C can be added to the right side of each equation.

How about this?



Think of a drag racer

What about $v-t$



$$\text{Ave. Acceleration} = \frac{v_{i+1} - v_i}{t_{i+1} - t_i} = \frac{\Delta v}{\Delta t} \quad \text{in } \frac{m/s}{s} = m/s^2$$

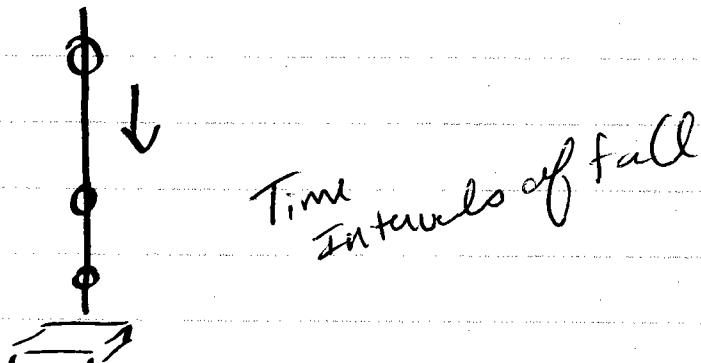
$$\text{inst. Accel.} = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t} = \frac{dv}{dt}$$

Acceleration has Magnitude and direction

$$a = \frac{dv}{dt} = \frac{d\left(\frac{dx}{dt}\right)}{dt} = \frac{d^2x}{dt^2}$$

deceleration vs. acceleration in negative direction

demo Mb-12

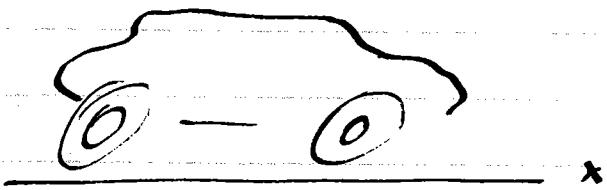


$x \sim$ Position	m	ft	mi
$v \sim$ Velocity	m/s	ft/s	mi/hr
$a \sim$ acceleration	m/s^2	ft/s^2	mi/hr^2
$t \sim$ time	s	s	hr

These are the kinematic variables. If you know these ... you know all there is to know about particle motion

Example

Sister w/ learner's permit
and obnoxious brother with radar
device



$$x(t) = At^2 \neq Bt^3$$

what bothers you abt this eqn?

perhaps A, B are bathesome
constants ... written as a variable symbol

What are units on A + B

if x is in ft s in ft/s^2 B is ft/s^3

Dimensional Analysis!

~~for A & B~~

lets say $x(t)$ is in feet for now
and

$$\cancel{A} = 10 \text{ ft/s}^2$$

$$B = 1 \text{ ft/s}^3$$

bothered by feet
change to meters

$$1 \text{ foot} \times \frac{12 \text{ in}}{1 \text{ ft}} \times \frac{2.54 \text{ cm}}{1 \text{ in}} \times \frac{1 \text{ m}}{100 \text{ cm}} = 0.3 \text{ m}$$

 factor label method

$$A \frac{\text{ft}}{\text{s}^2} = 10 \frac{\text{ft}}{\text{s}^2} \times \frac{0.3 \text{ m}}{1 \text{ ft}} = \underline{\underline{3}} \text{ m/s}^2$$

$$B \frac{\text{ft}}{\text{s}^3} = 1 \frac{\text{ft}}{\text{s}^3} \times \frac{0.3 \text{ m}}{1 \text{ ft}} = 0.3 \text{ m/s}^3$$

Find average velocity, ~~Accel~~ Accel over 4 s interval
and
(from t=0)

Find inst. posn., Vel., Accel at t=0, 1, 2, 3, 4

Posn.
= $x(t) = 3t^2 - 0.3t^3$

<u>t (s)</u>	<u>x(m)</u>
0	0
1	2.7
2	9.6
3	18.9
4	28.8

Ave. velocity
 \overline{x} over $\sum 4$ seconds

$$= \frac{28.8}{4} = 7.2 \text{ m/s}$$

in + x
direction